

Dirac notations in state space

Euclidean space $\sim 3D \sim \text{Real}$
State Space $\sim ND \sim \text{Complex}$

the vector space in which quantum systems live.

just like Euclidean space is for classical systems.

both the spaces inner product.

A vector space equipped with an inner product is an Hilbert space.

Postulate 1: The state of a physical system is characterized by a state vector that belongs to a complex vector space $\mathcal{V}$, called the state space of the system

Euclidean 3D space $\mathbb{R}^3$

state space $\sim$ Dirac not.

$\vec{u}$ "vector"

$|\psi\rangle$ "ket"

Scalar product in Euclidean space

$$SP(\vec{u}_1, \vec{u}_2) = \vec{u}_1 \cdot \vec{u}_2 = c \in \mathbb{R}$$

$$(x_1, y_1, z_1) \begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix} = c$$

① conjugation $SP(\vec{u}_1, \vec{u}_2) = SP(\vec{u}_2, \vec{u}_1)$
 $\vec{u}_1 \cdot \vec{u}_2 = \vec{u}_2 \cdot \vec{u}_1$

$$c = x_1 y_1 + x_2 y_2 + x_3 y_3$$

(addition is not defined,

so this means they must be in diff v space)

② linearity $SP(\vec{u}_1, a\vec{u}_2) = a SP(\vec{u}_1, \vec{u}_2)$
 $\vec{u}_1 \cdot (a\vec{u}_2) = a(\vec{u}_1 \cdot \vec{u}_2)$

$$SP(\vec{u}_1, \vec{u}_2 + \vec{u}_3) = SP(\vec{u}_1, \vec{u}_2) + SP(\vec{u}_1, \vec{u}_3)$$

③ positive $SP(\vec{u}_1, \vec{u}_1) \geq 0 \Rightarrow \vec{u}_1 \cdot \vec{u}_1 \geq 0 \Rightarrow |\vec{u}_1|^2 \geq 0$
 $\vec{u}_1 \cdot \vec{u}_1 = 0$ iff $\vec{u}_1 = 0$

scalar product in state space

$$SP(|\psi\rangle, |\varphi\rangle) = c, \quad c \in \mathbb{C}$$

① conjugation $SP(|\psi\rangle, |\varphi\rangle) = [SP(|\varphi\rangle, |\psi\rangle)]^*$

② linear but only in the second argument

$$SP(|\psi\rangle, a|\varphi\rangle) = a SP(|\psi\rangle, |\varphi\rangle)$$

$$\underline{SP(|\psi\rangle, |\varphi\rangle + |\chi\rangle)} = SP(|\psi\rangle, |\varphi\rangle) + SP(|\psi\rangle, |\chi\rangle)$$

only in second argument

Anti-linear in the first argument

$$SP(a|\psi\rangle, |\varphi\rangle) = [SP(|\varphi\rangle, a|\psi\rangle)]^*$$

move it to
second argument

that adds the
conjugation

$$\Rightarrow a^* [SP(|\varphi\rangle, |\psi\rangle)]^* \Rightarrow a^* SP(|\psi\rangle, |\varphi\rangle)$$

when scalar is in the first argument, we need to take its complex conjugate to take it out. That is why it is **Anti-linear in its first argument**.

③ Positive $SP(|\psi\rangle, |\psi\rangle) \geq 0 \quad = 0 \text{ iff } |\psi\rangle = 0$

$$u_1 \cdot u_2 = c \Rightarrow \underbrace{(x_1 \ y_1 \ z_1)}_{\text{row}} \underbrace{\begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix}}_{\text{column}} = c$$

$$c = x_1 x_2 + y_1 y_2 + z_1 z_2$$

but the addition is not defined on this hence they must be on diff vector spaces

"column" belongs to the vector space
 "row" belongs to the dual space

Linear map:

A row vector maps column vector to a scalar.

$$\begin{array}{ccc} \downarrow & & \swarrow \\ (x_1, y_1, z_1) & \begin{pmatrix} x_2 \\ y_2 \\ z_2 \end{pmatrix} & = c \\ \text{row} & \text{column} & \text{scalar.} \end{array}$$

$$\overbrace{SP(\mathcal{H}_1, 0)} \text{ maps } \underline{x_2} \text{ to } c$$

Linear maps. (the objects that act on a vector)
 $\mathcal{H} \longleftrightarrow SP(\mathcal{H}, 0)$

The set $\{ SP(\mathcal{H}, 0) \}$ forms a vector space: dual space.

Dual space to state space

$$SP(|\psi\rangle, |\varphi\rangle) = c \quad c \in \mathbb{C}$$

$$SP(|\psi\rangle, 0) \Rightarrow \langle \psi| \quad \text{dual vector.} \quad \text{"bra"} \quad \text{"row"}$$

$$SP(|\psi\rangle, |\varphi\rangle) \Rightarrow \langle \psi | \varphi \rangle \quad \text{bracket}$$

$$|\psi\rangle \in V \quad \rightarrow \quad \langle \psi| \in V^* \\ \text{(dual space)}$$

- scalar product is anti-linear in the first argument.

$$a|\psi\rangle \rightarrow a^* \langle \psi|$$

state space

dual space.

ket



bra

$|\psi\rangle$



$\langle\psi|$

$a|\psi\rangle$



$a^* \langle\psi|$

bracket : $\langle\psi|\psi\rangle = 1$